

Molecular shape and exoelectricity

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Monte Carlo simulations were performed of systems of wedge-shaped objects formed from Gay–Berne ellipsoids joined to Lennard–Jones spheres. We studied two different wedge shapes, one more asymmetric than the other. The bend and splay flexoelectric coefficients were measured in the isotropic and smectic phases using linear response theory, and found to be negligibly small in the isotropic phase. We found a close connection between the properties of the intermolecular potential and the flexoelectric coefficients measured in the smectic phase. In particular, negligible bend coefficients were found for both shapes and a larger magnitude of the splay coefficient for the more prominent wedge, in accord with Meyer's original mechanism for flexoelectricity. The less prominent wedge produced a splay flexoelectric coefficient with the opposite sign due to the attractive tail of the intermolecular potential and the relative narrowness of the molecular head.

duces an electrical polarization, similar to the phenomenon quadrupoles requiring neither the shape asymmetries of piezoelectricity in solid crystals. The flexoelectric effect nor the dipole moments of Mever's original arg of piezoelectricity in solid crystals. The flexoelectric effect nor the dipole moments of Meyer's original argument.
was first proposed by Meyer $[1]$ who considered asym-
Rather, molecular quadrupoles allow uneven charge was first proposed by Meyer $[1]$ who considered asym-
metric molecular quadrupoles allow uneven charge distri-
metric molecules either wedge-shaped with longitudinal butions leading to polarizations in any given volume dipole moments or 'banana' shaped with transverse when a splay is imposed (see figure 3).
dipoles. In the absence of a director deformation, the Both the Mever dipole and the Propacking of the molecules is similar to that of ellipsoidal- quadrupole mechanisms have been observed experishaped or rod-like molecules (the additional asymmetries mentally $[3-7]$. Typically, the flexoelectric coefficients of the molecules have negligible effect) and the average are measured over a range of temperature in the nematic polarization is zero. However, when a splay is imposed base and their variation compared with that of the upon a system of wedges or a bend upon a system of nematic order parameter *S*. Although it has been shown bananas, the preferred packing of the molecules results in that for both the dipole and quadrupole mechanisms a net alignment of dipoles leading to an overall polarization there are contributions to the flexoelectric coeff a net alignment of dipoles leading to an overall polarization there are contributions to the flexoelectric coefficients of the medium (see figures 1 and 2). Alternatively, an involving several powers of S. Marcerou and Pr of the medium (see figures 1 and 2). Alternatively, an involving several powers of *S*, Marcerou and Prost used applied electric field which aligns the dipoles induces a the dominant contributions—*S* for the quadrupole applied electric field which aligns the dipoles induces a the dominant contributions— S for the quadrupole splay or bend in the appropriately shaped system—this mechanism and S^2 for the dipole mechanism—in the splay or bend in the appropriately shaped system—this mechanism and S^2 for the dipole mechanism—in the is sometimes called the inverse flexoelectric effect. In analysis of their experimental data [4] They found is sometimes called the inverse flexoelectric effect. In analysis of their experimental data [4]. They found either case, the net polarization P and the elastic flexoelectric coefficients proportional to S for symmetric either case, the net polarization **P** and the elastic flexoelectric coefficients proportional to *S* for symmetric, deformations are related by the flexoelectric coefficients non-polar molecules clearly demonstrating the q e_{11} and e_{33} i e_{11} and e_{33} introduced by Meyer through the following mechanism. Quadratic variation with *S* was seen for tinear response relation:

$$
\mathbf{P} = e_{11} \hat{\mathbf{n}} (\nabla \quad \hat{\mathbf{n}}) + e_{33} \hat{\mathbf{n}} \times (\nabla \times \hat{\mathbf{n}})
$$
 (1) moments.
In the s

1. Introduction Subsequent to Meyer's work, Prost and Marcerou [2] In the flexoelectric effect a director deformation pro-
proposed a flexoelectric mechanism based on molecular proposed a flexoelectric mechanism based on molecular butions leading to polarizations in any given volume

> Both the Meyer dipole and the Prost and Marcerou phase and their variation compared with that of the non-polar molecules, clearly demonstrating the quadrupole banana-shaped molecules with strong, transverse dipole

 $\mathbf{P} = e_{11} \hat{\mathbf{n}} (\nabla \hat{\mathbf{n}}) + e_{33} \hat{\mathbf{n}} \times (\nabla \times \hat{\mathbf{n}})$ (1) moments.
In the smectic A phase, an additional flexoelectric
oefficient arises representing the coupling between the where **n** is the director. The first term on the right hand coefficient arises, representing the coupling between the side of this equation corresponds to splay flexoelectricity net polarization and variations in the smect side of this equation corresponds to splay flexoelectricity and polarization and variations in the smectic layer
(relevant for wedges) and the second term to bend spacing [6.8–10] Specifically there is an additional (relevant for wedges) and the second term to bend spacing $[6, 8-10]$. Specifically, there is an additional flexoelectricity (relevant for bananas). contribution to the right-hand side of equation (1) proportional to $\left(\frac{\partial^2 u}{\partial z^2}\right) \hat{z}$, where *u* is the displacement *Author for correspondence; of the smectic layers whose normals are parallel to the e-mail: pelcovits@physics.brown.edu **zˆ** axis. Prost and Pershan [6] found this additional term

Figure 2. (*a*) 'Bananas' with trans verse dipoles under normal nematic conditions; there is no bend and no net polarization. (*b*) Under an applied bend, the preferred banana alignment results in a net polarization; alternatively, an applied field induces a bend due to the banana shape of the molecules. (*a*) (*b*)

central 'layer', plus charges from above are allowed to enter, while plus charges below are expelled, leading to a

the smectic C phase involves a total of 14 coefficients flexoelectric coefficients were evaluated using microand is discussed in [9]. scopic expressions based on density functional theory,

A systematic method for calculating flexoelectric coefficients based on molecular shape and multipole properties would be very valuable. Mean-field theories $[2, 11-14]$ do not consider the short range fluctuations in molecular alignment which can be quite important. Computer simulations offer a way to assess the molecular origins of flexoelectricity. In particular, simulations can focus strictly on Meyer's packing ideas without the complication of dipolar interactions which could lead to antiparallel alignment of side-by-side molecules. To date, only one simulation study $[15]$ of flexoelectricity has been carried out. In this study the flexoelectric coefficients were evaluated for wedge-shaped molecules Figure 3. Quadrupoles with a splay imposed. Within the interacting via a generalized Gay–Berne potential [16].

Figure 3. Quadrupoles with a splay imposed. Within the interacting via a generalized Gay–Berne potential [16] enter, while plus charges below are expelled, leading to a ours) by a Gay–Berne ellipsoid with a Lennard–Jones

such experiment polarization upwards. sphere attached near one end (see figure 4). Two sets of parameters were considered in [15], one with a slightly to be negligible experimentally. The flexoelectricity of more pronounced wedge shape than the other. The

Figure 4. Illustration of the basic geometric parameters of the wedge-shaped molecule composed of a rod and sphere.

and a larger value of e_{11} was obtained for the more
propounced wedge. The band flavoelectric coefficient pronounced wedge. The bend flexoelectric coefficient was nearly zero, in agreement with Meyer's suggestion that bend flexoelectricity should not appear in a system

the study in several ways. First, we evaluate the flexo-
shape of the rods. Its explicit form is electric coefficients using linear response theory and the fluctuation–dissipation theorem, which provide a com-) putationally simpler and more direct means of evaluation compared with density functional theory. Second, we consider two model sets of molecular parameters, one representing a molecule with significantly more asymmetry than either molecule considered in $[15]$. By exploring the intermolecular potentials for our two sets of parameters we find that the less prominent wedges (similar to the less prominent ones considered in [15]) Here σ_{\parallel} is the separation between two rods when they prefer to align with their larger ends tilted *toward* each are oriented end-to-end with $U_{\text{rod1-rod2}} = 0$, and σ_{\perp} is the other (because of the short range attractive interaction), corresponding separation when the while the more prominent wedges prefer to align with by-side. The well depth $\varepsilon(\hat{\mathbf{u}}_1, \hat{\mathbf{u}}_2, \hat{\mathbf{r}})$, representing the their larger and tilted sure from each other (in this conjections of the ettrective inter their larger ends tilted *away* from each other (in this anisotropy of the attractive interactions, is written as case the repulsive hard core interaction dominates).
These opposing tendencies in turn lead to opposite $\epsilon(\hat{\mathbf{u}}_1, \hat{\mathbf{u}}_2, \mathbf{r}) = \epsilon_0 \epsilon^{\nu}(\hat{\mathbf{u}}_1, \hat{\mathbf{u}}_2) \epsilon^{\prime \mu}(\hat{\mathbf{u}}_1, \hat{\mathbf{u}}_2, \hat{\mathbf{r}})$ (6) signs of the splay flexoelectric coefficients. While Meyer's where original argument considered only repulsive hard core interactions, it is consistent with his ideas to expect this difference in signs if attractive forces are also included. and As in [15], and also consistent with Meyer's ideas, we find a negligible value of the bend flexoelectric coefficient.

The outline of this paper is as follows. In the next section we present the details of our modelling of wedgeshaped molecules. Section 3 discusses the linear response theory used to measure the flexoelectric coefficients in shaped molecules. Section 3 discusses the linear response
theory used to measure the flexoelectric coefficients in side-by-side well depths, respectively, as
our simulation. Our results are presented in 8.4 and we our simulation. Our results are presented in § 4 and we offer some concluding remarks in the final section.

2. Molecular shape modelling

Using an approach similar to that of [15] we constructed a wedge-shaped molecule from a standard Gay– Berne ellipsoid (or rod) with a sphere added near one end (see figure 4). The net interaction potential between two wedge-shaped molecules labelled 1 and 2 then consists of four terms, namely

$$
U_{\text{tot}} = U_{\text{rod1-rod2}} + U_{\text{sphere1-sphere2}} + U_{\text{rod1-sphere2}} + U_{\text{sphere1-rod2}} \tag{2}
$$

where $U_{\text{rod1-rod2}}$ is given by the original Gay–Berne potential [17]:

$$
U_{\text{rod1-rod2}}(\hat{\mathbf{u}}_1, \hat{\mathbf{u}}_2, \mathbf{r}) = 4\varepsilon(\hat{\mathbf{u}}_1, \hat{\mathbf{u}}_2, \hat{\mathbf{r}})
$$

$$
\times \left\{ \left[\frac{\sigma_o}{r - \sigma(\hat{\mathbf{u}}_1, \hat{\mathbf{u}}_2, \hat{\mathbf{r}}) + \sigma_o} \right]^{12} - \left[\frac{\sigma_o}{r - \sigma(\hat{\mathbf{u}}_1, \hat{\mathbf{u}}_2, \hat{\mathbf{r}}) + \sigma_o} \right]^6 \right\} (3)
$$

where $\hat{\mathbf{u}}_1$, $\hat{\mathbf{u}}_2$ give the orientations of the long axes of was nearly zero, in agreement with Meyer's suggestion rods 1 and 2, respectively, and $\mathbf{r} = \mathbf{r}_1 - \mathbf{r}_2$, with the the head flavor learning the solution of the nede learning a series of the nede learning the solutio r_1 and r_2 . The of wedges.
 Example 2 of the separation between the rods
 Example 2 of th In this paper we consider a similar model but extend at which the potential vanishes, and thus represents the

$$
\sigma(\hat{\mathbf{u}}_1, \hat{\mathbf{u}}_2, \hat{\mathbf{r}}) = \sigma_o \left\{ 1 - \frac{1}{2} \chi \left[\frac{(\hat{\mathbf{r}} \quad \hat{\mathbf{u}}_1 + \hat{\mathbf{r}} \quad \hat{\mathbf{u}}_2)^2}{1 + \chi(\hat{\mathbf{u}}_1 \quad \hat{\mathbf{u}}_2)} + \frac{(\hat{\mathbf{r}} \quad \hat{\mathbf{u}}_1 - \hat{\mathbf{r}} \quad \hat{\mathbf{u}}_2)^2}{1 - \chi(\hat{\mathbf{u}}_1 \quad \hat{\mathbf{u}}_2)} \right] \right\}^{-1/2}
$$
(4)

 $\sigma_{\sigma} = \sigma_{\perp}$ (defined below) and χ is

$$
\chi = [(\sigma_{\parallel}/\sigma_{\perp})^2 - 1]/[(\sigma_{\parallel}/\sigma_{\perp})^2 + 1]. \tag{5}
$$

corresponding separation when the two rods are side-

$$
\varepsilon(\hat{\mathbf{u}}_1, \hat{\mathbf{u}}_2, \mathbf{r}) = \varepsilon_o \varepsilon^{\nu}(\hat{\mathbf{u}}_1, \hat{\mathbf{u}}_2) \varepsilon^{\prime \mu}(\hat{\mathbf{u}}_1, \hat{\mathbf{u}}_2, \hat{\mathbf{r}})
$$
(6)

$$
\varepsilon(\hat{\mathbf{u}}_1, \hat{\mathbf{u}}_2) = \left[1 - \chi^2(\hat{\mathbf{u}}_1 \hat{\mathbf{u}}_2)^2\right]^{-1/2} \tag{7}
$$

$$
\varepsilon'(\hat{\mathbf{u}}_1, \hat{\mathbf{u}}_2, \hat{\mathbf{r}}) = 1 - \frac{1}{2} \chi' \left[\frac{(\hat{\mathbf{r}} \quad \hat{\mathbf{u}}_1 + \hat{\mathbf{r}} \quad \hat{\mathbf{u}}_2)^2}{1 + \chi'(\hat{\mathbf{u}}_1 \quad \hat{\mathbf{u}}_2)} + \frac{(\hat{\mathbf{r}} \quad \hat{\mathbf{u}}_1 - \hat{\mathbf{r}} \quad \hat{\mathbf{u}}_2)^2}{1 - \chi'(\hat{\mathbf{u}}_1 \quad \hat{\mathbf{u}}_2)} \right]
$$
(8)

$$
\chi' = [1 - (\varepsilon_{\parallel}/\varepsilon_{\perp})^{1/\mu}]/[1 + (\varepsilon_{\parallel}/\varepsilon_{\perp})^{1/\mu}]. \tag{9}
$$

We measure all of our physical quantities in reduced To ascertain the effective shape of the composite rod– by Gay and Berne [17]: $\mu = 2$, $\nu = 1$, and $\varepsilon_{\perp}/\varepsilon_{\parallel} =$

$$
U_{\text{sphere1-sphere2}}(\mathbf{r}) = 4\varepsilon_o \left[\left(\frac{d}{r} \right)^{12} - \left(\frac{d}{r} \right)^6 \right] \tag{10}
$$

where *d* is the separation between the two spheres at Comparing figures 7 and 8 with figure 9, we note that which the potential $U_{\text{sphere1-sphere2}}$ vanishes; i.e. it is a in the twist (b) and bend (c) configurations there is l measure of the diameter of the sphere. The relative right symmetry about 180[°], which is to be expected position vector **r** is measured from the centre of sphere 1

 $_{rs}(\hat{\mathbf{u}}_1, \mathbf{r}_{12})$ meter $\varepsilon_{rs}(\hat{\mathbf{u}}_i, \hat{\mathbf{u}}_j)$ is

$$
\sigma_{rs}(\hat{\mathbf{u}}_1, \hat{\mathbf{r}}) = \sigma_o^{rs} (1 - \chi_{rs}(\hat{\mathbf{r}} \quad \hat{\mathbf{u}}_1))^{-1/2}
$$
(11)

$$
\varepsilon_{rs}(\hat{\mathbf{u}}_1, \hat{\mathbf{r}}) = 1 \tag{12}
$$

with χ _{rs} defined as

$$
\chi_{\rm rs} = \frac{\sigma_{\parallel}^2 - \sigma_{\perp}^2}{\sigma_{\parallel}^2 + d^2} \tag{13}
$$

$$
\sigma_o^{\rm rs} = \frac{1}{\sqrt{2}} (\sigma_\perp^2 + d^2)^{1/2}.
$$
 (14)

parameters: a slightly wedge-shaped object with $\sigma_1 = 1.0$, case it is a reasonable result. For the more prominent the centre of the sphere was located at a distance $D = 1.3$ from the centre of the rod, and at a distance $D = 1.2$ in While the absolute minima of the pair potentials for the latter case. In terms of the steric dipole moment the two sets of wedge parameters correspond to non-

units in terms of the energy scale ε_0 and the length scale sphere molecule we computed equipotential contours σ_0 . For the adjustable parameters appearing in equations (with contour values close to zero). The cont (6), (8) and (9), we used the values originally proposed are shown for the two sets of parameters in figures 5 and 6, clearly indicating a wedge-like shape. To explore the interaction and local packing of the molecules we choices for the rod shape parameters σ_{\parallel} and σ_{\perp} are the interaction and local packing of the molecules we discussed below. The interaction $U_{\text{sphere1-sphere2}}$ is given by the ordinary for several different relative orientations of a pair of nonecules with relative tilt θ . The results for the two sets molecules with relative tilt θ . The results for the two sets of molecular parameters are shown in figures 7 and 8. For the purposes of comparison corresponding curves for the original Gay–Berne potential $U_{\text{rod}1\text{-rod}2}$ are shown in figure 9.

in the twist (b) and bend (c) configurations there is left– given that all three molecular shapes are rotationally to the centre of the sphere 2.

The interaction between the rod-like part of one molecule

and the sphere of the other molecule, $U_{\text{rod1-sphere2}}$, is

given by a Gay-Berne potential generalized to mimic

the interaction betw figuration, figures 7(*a*) and 8(*a*), the wedges do not exhibit the left–right tilt symmetry ($\theta \rightarrow \theta + 180^{\circ}$) seen of the corresponding parameters in equations (4) and

(6), namely [16]:

This result is not surprising: tilting the larger end of one wedge *away* from the larger end of another wedge (corresponding to θ < 180° in the figures) should yield a and different energy than tilting the larger ends *toward* each other. More importantly, for each set of wedge parameters there is an absolute minimum in the potential energy corresponding to a finite but small splay angle. For the more prominent wedge shape, figure $8(a)$, this angle is approximately 10° ; i.e. the pair of wedges prefer to align with their larger ends tilted away from each other. For the less prominent wedge shape, figure 7(*a*), the angle corresponding to the absolute minimum is nearly 360°; i.e. the wedges prefer to align with their larger ends tilted *toward* each other. As we shall see below, this difference yields flexoelectric coefficients of opposite In the rod–sphere potential the relative position vector signs for the two molecular shapes. While it might seem **r** is measured for the centre of the rod to the centre of surprising at first glance that the less prominent wedges the sphere. the sphere the sphere. the sphere the sphere. the sphere interaction is the sphere. We performed simulations for two sets of molecular between two spheres and the fact that $d < \sigma_{\perp}$, in this σ_{\parallel} = 2.6, *d* = 0.94, and a more prominent wedge with wedges the larger repulsive core of the spheres leads to parameters $\sigma_{\perp} = 1.0$, $\sigma_{\parallel} = 2.4$, $d = 1.3$. In the former case the expected tilting of the larger ends away from each the centre of the sphere was located at a distance $D = 1.3$ other.

 $p^* = (4\pi/3)(d/2)^3D$ introduced in [15], our parameters zero splay, note that this state is only slightly preferred correspond to values of *P** of 0.565 and 1.38 respectively over the aligned state, $\theta = 0^{\circ}$, for the parameters of (in [15] systems with dipole moments of 0.524 and 0.662 figure 7(*a*) and the antiparallel aligned state, $\theta = 180^\circ$, were studied). **for the more prominent wedge of figure 8(***a***). There**

Figure 5. Potential energy contours showing the shape of the rod–sphere composite with parameters $\sigma_{\perp} = 1.0$, $\sigma_{\parallel} = 2.6$, $d = 0.94$: (*a*) side view showing wedge-like asymmetry;

(*b*) top view showing axial symmetry. The top view **3. Calculation of flexoelectric coefficients** (*b*) top view showing axial symmetry. The top view **10** measu contours are not completely circular due to a finite number

is also a substantial subsidiary potential minimum for to the orientational strain which yields flexoelectricity. antiparallel slightly wedge-shaped molecules. In our Thus, a calculation of the relevant correlation functions simulations in the absence of an external electric field yields the flexoelectric coefficients.

Figure 6. Potential energy contours showing the shape of the rod–sphere composite for a more prominent wedge with parameters $\sigma_{\perp} = 1.0$, $\sigma_{\parallel} = 2.4$, $d = 1.3$.

of a system of 256 wedge-shaped molecules using both sets of molecular parameters, we found, as expected on symmetry grounds, no net spontaneous splay or electric polarization (assuming molecular dipole moments parallel to the long axis of the wedge). However, if an electric field were applied to the system of prominent wedges, we would expect the potential well corresponding to non-zero splay to become deeper relative to that of the antiparallel state $\theta = 180^\circ$, leading to splay flexoelectricity. For the slightly wedge-shaped objects of figure 7, the shallowness of the well corresponding to non-zero splay makes it less obvious that splay flexoelectricity will exist. However, in our simulations we do in fact splay flexoelectricity in this case, albeit smaller than in the case of the more prominent wedges and with the opposite sign.

We now turn to a discussion of how to extract the flexoelectric coefficients from our simulations.

of sample points. The side view data were generated by we used the linear response theory of Nemtsov and fixing one wedge in the *yz* plane as shown, while a second Osipov $[18]$. The flexoelectric coefficients in this method wedge pointing up out of the plane and with its narrow are related to the response function of the s wedge pointing up out of the plane and with its narrow
end just touching the plane 'scanned' across the first
wedge. For the top view data, both wedges were parallel;
orientational stress. Using the fluctuation-dissipation one remained fixed while the other was moved around
theorem, the response function can be found from cor-
relation functions of the polarization density and the
the first in the same plane. relation functions of the polarization density and the orientational stress tensor. The latter tensor is conjugate

Figure 7. Minimum well depths (calculated as a function of molecular separation) for molecular parameters $\sigma_{\perp} = 1.0$,

 θ

225

 $\frac{1}{225}$

270

 315

 $\overline{360}$

 θ

270

 315

 $\overline{360}$

Figure 8. The same as figure 7 but for the more prominent wedges shown in figure 6, with parameters $\sigma_{\perp} = 1.0$, $\sigma_{\parallel} = 2.6$, $d = 0.94$ for various relative orientations as wedges shown in figure 6, with parameters $\sigma_{\perp} = 1.0$, shown: (*a*) splay, (*b*) twist and (*c*) bend configurations. $\sigma_{\parallel} = 2.4$, $d = 1.3$.

with parameters $\sigma_{\perp} = 1.0, \sigma_{\parallel} = 3.0$.

Specifically, the splay and bend flexoelectric coefficients in the Nemstov–Osipov formalism are given by

$$
e_{11} = -E_{\alpha\beta\gamma}e_{\mu\beta\gamma}n_{\alpha}n_{\mu}/2
$$

\n
$$
e_{33} = E_{\alpha\beta\gamma}e_{\alpha\beta\mu}n_{\gamma}n_{\mu}/2
$$
\n(15)

where we use the summation convention over the Greek indices (summed over the coordinate directions *x*, *y* and *z*). The tensor $e_{\alpha\beta\gamma}$ is the antisymmetric Levi–Civita tensor, while the antisymmetric tensor $E_{\alpha\beta\gamma}$ is the response function satisfying

$$
P_{\alpha} = E_{\alpha\beta\gamma} \gamma_{\beta\gamma} \tag{16}
$$

where $\gamma_{\alpha\beta}$ is the orientational strain tensor given by

$$
\gamma_{\alpha\beta} = \frac{\partial \theta_{\alpha}}{\partial x_{\beta}}.
$$
 (17)

Here θ_{α} denotes the rotation angle of the director about the coordinate axis labelled by α . For small director deformations $\delta \hat{\mathbf{n}}$, $\theta \sim \sin \theta \sim \hat{\mathbf{n}} \times \delta \hat{\mathbf{n}}$, which then yields

$$
\gamma_{\beta\gamma} = e_{\beta\mu\nu} n_{\mu} \frac{\partial n_{\nu}}{\partial x_{\gamma}}.
$$
 (18)

Symmetry considerations show that $E_{\alpha\beta\gamma}$ has four independent components in the nematic and smectic A phases.

Using the fluctuation-dissipation theorem the components of the response function $E_{\alpha\beta\gamma}$ are given by correlation functions of the orientational stress tensor and polarization:

$$
E_{\alpha\beta\gamma} = -\frac{\beta}{V} \langle \pi_{\beta\gamma} \mathscr{P}_{\alpha} \rangle. \tag{19}
$$

Here $\beta = 1/k_B T$, *V* is the volume of the system, $\mathcal{P} = \sum_i \mu_i$, $(\mu_i$ is the dipole moment of molecule *i*), and $\pi_{\alpha\beta}$ is the static orientational stress tensor given by

$$
\pi_{\alpha\beta} = \frac{1}{2} \sum_{i \neq j} r_{ij\beta} \tau_{ij\alpha}.
$$
 (20)

In equation (20) r_{ij} is the relative position vector of molecules *i* and *j*, and τ_{ij} is the torque exerted by molecule *j* on *i*.

In our simulations, then, we calculate the components $E_{\alpha\beta\gamma}$ of the response function by computing the correlation functions in equation (19) as time averages (or MC cycle averages) and then calculate e_{11} and e_{33} from equation (15) (the director is also computed during the simulations). We set the magnitude of the molecular Figure 9. The same as figure 7 but for Gay–Berne molecules dipole moment to unity; its direction is given by \hat{u} , the long axis of the wedge. The torque on molecule *i* due to

our generalized potential U_{tot} is given by [19],

$$
\tau_i = \sum_{i \neq j} \tau_{ij} = \mathbf{\hat{u}}_i \times (-\nabla_{\mathbf{\hat{u}}} U_{\text{tot}}).
$$
 (21)

4. Results

We performed constant temperature and pressure (with $P^* = P\sigma_0^3/\varepsilon_0 = 10$) Monte Carlo simulations on
existence of 256 wedges using the two sets of molecular systems of 256 wedges, using the two sets of molecular parameters described in § 2. The systems were equilibrated for 250 000–500 000 cycles and cooled in dimensionless temperature steps of 0.1 (the dimensionless temperature is defined by $T^* = k_B T / \epsilon_0$). As in [15] we found a strong
proference for the system to form a smootic A phase preference for the system to form a smectic A phase, even when the attractive part of the potential was removed (in the ordinary GB system, removal of the attractive forces tends to stabilize the nematic phase $[20]$). The use of a different set of Gay–Berne parameters for the attractive portion of the potential $[21]$ (which enhance the stability of the nematic phase for a system of GB ellipsoids) did not stabilize the nematic phase in the present case of wedge-like molecules—another indication that the repulsive core shape is the dominant factor in the possible formation of a nematic phase.

Stelzer *et al*. [15] found that the nematic phase is absent for dipole moment $p^* = 0.814$, though they were able to produce nematic phases over narrow temperature ranges for $p^* = 0.524$ and 0.662. Thus, our inability to produce a stable nematic phase for our molecules with $p^* = 1.38$ is consistent with [15], but our inability to produce a stable nematic for our less asymmetric shape with $p^* = 0.565$ is not; the reason for this discrepancy is not clear. We note that experimentally the splay and bend flexoelectric coefficients in the nematic and smectic phases have been found to be virtually identical $[6]$, while the additional flexoelectric coefficient which appears in the smectic A phase but not in the nematic is negligibly small. Thus, we proceeded to measure the splay and bend flexoelectric coefficients in the smectic phase using the method outlined in § 3.

Interestingly, the smectic layers show a distinct domain structure, see figure $10(a)$. Each domain is characterized by a non-zero splay of the same sign, but the net direction of the orientation vectors $\hat{\mathbf{u}}$ whose heads correspond to the wide ends of the wedges flips from one
domain to the next. This domain structure is not
domain to the next. This domain structure is not observed in the Gay–Berne smectic, figure 10(*b*). Recall **u** $\hat{\mathbf{u}}$ whose heads correspond to the wide ends of the wedges. from figures $7(a)$ and $8(a)$, that neighbouring wedges The domains in the wedge case can be clearly seen. prefer splay. The alternation of the net direction of the molecular orientation vectors between domains maintains splay is thermally activated and should be expected to parallel smectic layers and zero net electric polarization. appear in a system that exhibits splay flexoelectricity. Note that this domain structure occurs in the absence It represents the essential physics of the fluctuationof an externally applied elastic deformation or electric dissipation theorem that relates the flexoelectric coefficients field. While on average there is no spontaneous splay in (that would be measured in the presence of an external the system, there is local spontaneous splay. This local field) to the thermal fluctuations of the director.

(*b*)

Data for the small ($p^* = 0.565$) and large ($p^* = 1.38$) wedges and for Gay-Berne ellipsoids are shown in the table. The Gay-Berne ellipsoids interact via the rod potential equation (3) with parameters $\sigma_{\perp} = 1.0$, $\sigma_{\parallel} = 3.0$, $\mu = 2$, and $\nu = 1$. We note that the values of the flexoelectric coefficients for the system of ellipsoids are zero to within the computed error; thus, in accord with Meyer's ideas, this system of symmetric objects does not exhibit flexoelectricity. In the isotropic phase both the large and small wedges also exhibit no flexoelectricity. However, in the smectic phases of both wedges splay flexoelectricity appears. Note the difference in sign between the e_{11} data in the smectic phase for the large and small wedges, consistent with their opposite splays. The actual values for the signs also are as expected: considering again figure 1 with the director $\hat{\bf{n}}$ taken to point upwards, the splay shown is then positive and the resulting polarization is parallel to $\hat{\mathbf{n}}$, implying that $e_{11} > 0$, see equation (1); this is the case for the large wedge. For the small wedge, the splay is negative but the polarization is still parallel to $\hat{\mathbf{n}}$, implying e_{11} < 0 as observed. The magnitude of e_{11} is also larger for the large wedge, consistent with Meyer's excluded volume mechanism for flexoelectricity. The average values for e_{33} , the bend flexoelectric coefficient, are much smaller in the smectic phases than the corresponding e_{11} values and are zero to within the computed error. This result is consistent with the uniaxial symmetry of our wedges and is a simple check of our approach to calculating flexoelectric coefficients. We also note that the bend coefficients varied in sign over the course of the simulation whereas the values of e_{11} maintained a consistent sign during the runs.

5. Conclusion

By simulating a system of wedge-like molecules formed from Gay–Berne ellipsoids and Lennard–Jones spheres we have explored some of the molecular origins of flexoelectricity. We measured both the bend and splay flexoelectric coefficients using linear response theory, which yields the coefficients in terms of correlation functions of the molecular torque and orientation vector. We studied wedges with two different parametrizations, and found a close connection between the properties of the intermolecular potential and the flexoelectric response of the system. In particular, wedge-shaped molecules do not produce a measurable bend flexoelectric coefficient, and a more prominent wedge-shaped object produces a larger splay flexoelectric coefficient, in accord with Meyer's original ideas on the origins of flexoelectricity. In the case of the less prominently shaped wedge we have obtained a splay flexoelectric coefficient with the opposite sign to that of the more prominent wedge due to the attractive tail of the intermolecular potential and the relative narrowness of the molecular head.

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